





# 02 Electric Grippers

<b>Electric Grippers</b>  <b>P.02-002</b>	<b>New Products</b>  <b>RoHS 10</b>	<b>New Products</b>  <b>RoHS 10</b>	<b>New Products</b>  <b>RoHS 10</b>	<b>New Products</b> 
	<b>Parallel Type</b> P.02-008	<b>Rotary Type</b> P.02-011	<b>Vacuum Suction Type</b> P.02-013	<b>Parallel Type with Brake</b> P.02-015

## 2025 Cost-Effective Solutions

### Electric Gripper Parallel Type

Rep Part: E-ELGPS40-050-T0-L5



Index: 2 / Page: 02-008

The electric gripper is a motor-driven clamp which allows flexible adjustment of stroke, speed, and clamping force, enabling quick operation mode changes.

Clamping force: 50N, Max. Stroke: 40mm, Cable length: 5m

**1,710.38 MYR/pc**

Qty	1-9	10~
DC	-	15%

### Electric Gripper Rotary Type

Rep Part: E-ELGPRS8-023-T0-L5



Index: 2 / Page: 02-011

The electric gripper is a motor-driven clamping device which allows flexible adjustment of stroke, speed, and clamping force, and supports angular rotation, enabling quick and versatile operation mode changes.

Clamping force: 23N, Max. Stroke: 8mm, Cable length: 5m

**4,664.24 MYR/pc**

Qty	1-9	10~
DC	-	15%

### Electric Gripper Vacuum Suction Type

Rep Part: E-ELGVS01-T1-L5



Index: 2 / Page: 02-013

The electric gripper with vacuum suction uses negative air pressure to pick and place workpieces without mechanical clamping. It is ideal for handling delicate or irregularly shaped objects, ensuring gentle contact, adjustable suction pressure, and high-speed operation in automation systems.

Max load: 1kg, Cable length: 5m

**2,457.36 MYR/pc**

Qty	1-9	10~
DC	-	15%

### Electric Gripper Parallel Type with Brake

Rep Part: E-ELGPPHS26-050-T1-L1



Index: 2 / Page: 02-015

The electric gripper with built-in brake is a motor-driven clamp which allows flexible adjustment of stroke, speed, and clamping force, enabling quick operation mode changes and maintaining position securely when power is off.

Clamping force: 50N, Max. Stroke: 26mm, Cable length: 1m

**3,183.22 MYR/pc**

Qty	1-9	10
DC	-	15%

## Economy series Electric Grippers

Force and position are adjustable

No need compressed air source

Easy to install, connect and control

New  
Products



### Product introduction

Electrical product, no compressed air source required

#### Parallel Type



- Positioning repeatability  $\pm 0.02$
- Force and position are adjustable

#### Brake Type



- Positioning repeatability  $\pm 0.02$
- Force and position are adjustable
- Maintaining position securely when power is off

#### Rotary Type



- Positioning repeatability  $\pm 0.02$
- Force and position are adjustable
- Rotation angle accuracy  $\pm 0.5^\circ$
- Maximum rotation speed  $1,500^\circ/\text{s}$
- Supports forward/reverse rotation infinite single-direction rotation

### Vacuum Suction Type

Vacuum level can be adjusted easily



- Vacuum Pressure  $-10 \sim -60 \text{ kPa}$
- Maximum load **1kg**
- Power **3.5W**



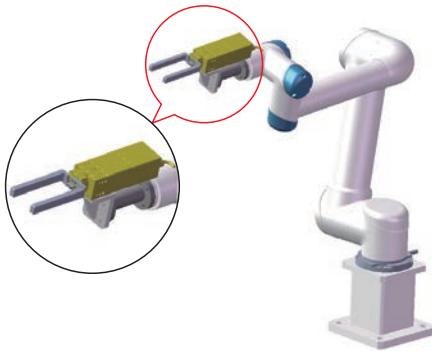
- Vacuum Pressure  $-10 \sim -70 \text{ kPa}$
- Maximum load **8kg**
- Power **12W**

## Example of Use

Can be used with robot or linear actuator

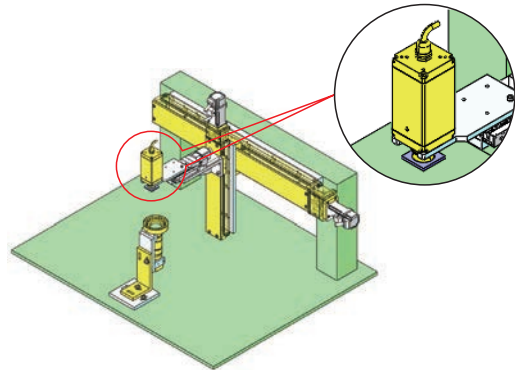
### ◇ Used in conjunction with robot

Completing pick-and-place task and assembly with collaborative robots

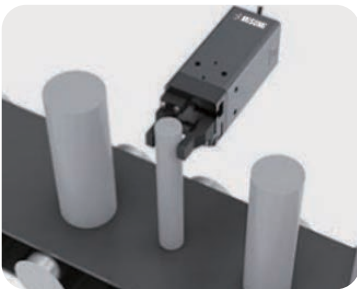


### ◇ Used with linear actuator

Used with linear actuator for workpiece suction and placement application



### ◇ Horizontal clamping



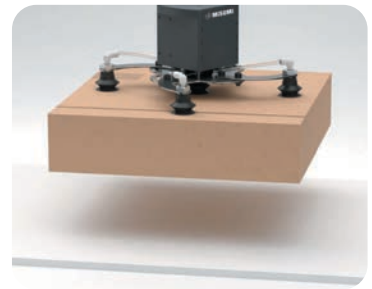
Stroke is adjustable for various workpiece sizes

### ◇ Rotary clamping



Can rotate left or right to open or close lids

### ◇ Vacuum suction



Air path extendable



Clamping force is adjustable for thin workpieces



Adjustable clamping force, rotation speed, and angle for peeling tasks



Independent A and B chambers with dual control

## Product value optimization proposal

### Advantage ①: Reduced number of components

Easy to install, connect and control

Electric Gripper



PLC

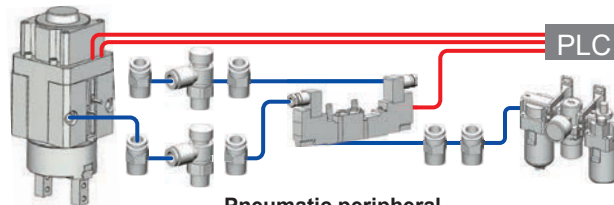
Software

# Vs

Representative Model: E-ELGPRS32-100-T0-L5  
3,885.74 MYR

Cost  
Reduced  
**55%**

Traditional  
pneumatic gripper



Main body + Pneumatic peripheral (10+ components) = Total  
6,588.42 MYR + 2,133.92 MYR = 8,722.34 MYR

— Electrical  
— Pneumatic

### Advantage ②: Reduced design time

Electric Gripper

Total time = **122min**

Select pneumatic components Design pneumatic circuits Pneumatic piping



# Vs

Total time = **250min**



Time  
Reduced  
**51%**

Traditional  
pneumatic gripper

Reduce downtime → Increased productivity

- ① One-click program switching for model change
- ② No sensor position adjustments required.



### Advantage ③: Low energy consumption



# Vs



Energy cost  
Reduced  
**95%**

Air compressor + vacuum generator combination  
Combined power: **251.2W**

MISUMI Electric Gripper Vacuum  
Power: **12W**

\*Product source (similar products are randomly purchased from the market)

## Parallel Type



- Adjustable stroke: 0~50mm, Clamping force: 1~100N
- Opening/closing positioning repeatability:  $\pm 0.02\text{mm}$
- Lifetime: Up to 30 million cycles
- Low power, energy-efficient

## Rotary Type



- Adjustable stroke: 0~32mm, Clamping force: 1~100N
- Opening/closing positioning repeatability:  $\pm 0.02\text{mm}$ , Rotational repeatability:  $\pm 0.5^\circ$
- Supports forward/reverse rotation, infinite single-direction rotation
- Low power, energy-efficient

## Vacuum Suction Type



- No air source required, easy to install
- Adjustable suction with real-time vacuum compensation to prevent workpiece from dropping
- Interchangeable head (supports different grippers) expandable air path
- Low power, energy-efficient
- Independent A/B chambers with dual-channel control

## Brake Type



- Adjustable stroke: 0~50mm Clamping force: 1~100N
- Opening/closing positioning repeatability:  $\pm 0.02\text{mm}$
- Maintaining position securely when power is off
- Low power, energy-efficient

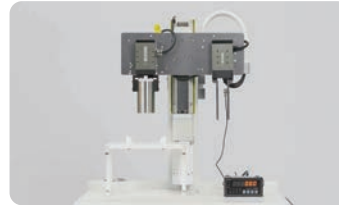
## Parallel Type

Electric Grippers used with robotic arm



Key Features: Adjustable and controllable stroke

Electric Grippers used with linear actuator



Key Features: Positioning repeatability:  $\pm 0.02\text{mm}$   
Stable clamping force

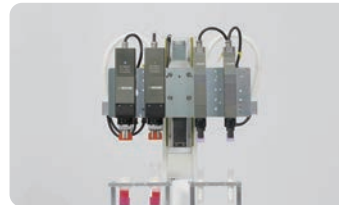
## Rotary Type

Electric Grippers used with robotic arm



Key Features: Positioning repeatability:  $\pm 0.02\text{mm}$   
Rotational repeatability:  $\pm 0.5^\circ$ , adjustable rotation angle

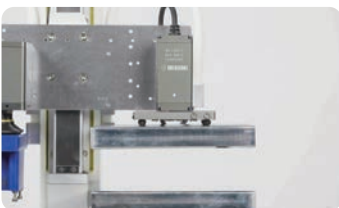
Electric Grippers used with linear actuator



Key Features: Supports forward /reverse rotation, unlimited single-direction rotation, applicable to the medical industry

## Vacuum Suction Type

Electric Grippers used with linear actuator



Key Features: Adjustable suction, suitable for battery case handling

Electric Grippers used with linear actuator



Key Features: Extendable air path for larger suction area and more stable handling

Electric Grippers used with robotic arm



Key Features: Adjustable suction, suitable for palletizing

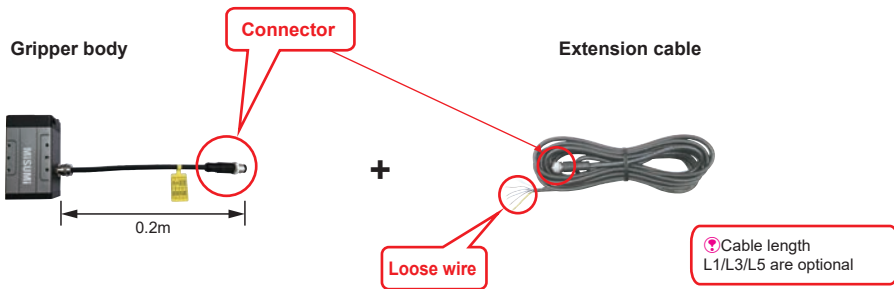
Electric Grippers used with linear actuator



Key Features: Independent A/B chambers with dual-channel control

## ■ Cable type classification

### With connector type



Electric gripper body with a 0.2m cable and connector + extension cable (connector on one side, loose wires on the other)

1 Type	2 Adjustable stroke (mm)	3 Clamping Force (N)	4 Communication Protocol	5 Cable Length (m)	Length (mm)	Width (mm)	Height (mm)
E-ELGPS (Connector Type)	26	015	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	35	35	92
		050			53	28	103.5
	40	050	T0: Modbus RTU(RS485)		50	35	87
		100					91.5
	50	060	T1: Modbus RTU(RS485)+I/O		70	40	97
		100					

## ■ Alterations



Alterations	Code	Spec.										
(1) Change the wiring outlet direction												
	UP DN LT RT	Change the wiring outlet direction. UP Upward DN Downward LT Left RT Right Ordering Code: UP-DN-LT-RT										
		<table border="1"> <thead> <tr> <th>Model</th> <th>ℓ(mm)</th> </tr> </thead> <tbody> <tr> <td>E-ELGPS26-050</td> <td>21</td> </tr> <tr> <td>E-ELGPS40-050</td> <td rowspan="2">31</td> </tr> <tr> <td>E-ELGPS40-100</td> </tr> <tr> <td>E-ELGPS50-060</td> <td rowspan="2">30</td> </tr> <tr> <td>E-ELGPS50-100</td> </tr> </tbody> </table>	Model	ℓ(mm)	E-ELGPS26-050	21	E-ELGPS40-050	31	E-ELGPS40-100	E-ELGPS50-060	30	E-ELGPS50-100
Model	ℓ(mm)											
E-ELGPS26-050	21											
E-ELGPS40-050	31											
E-ELGPS40-100												
E-ELGPS50-060	30											
E-ELGPS50-100												
		*Only parallel type support wire outlet direction change.										

Alterations	Code	Spec.
(2) Include protocol converter		
Standard: Only the electric gripper body and extension cable After change: Additional EtherCAT to Modbus RTU (RS485) protocol converter	EC	Include protocol converter Ordering Code EC Supports EtherCAT and Modbus RTU (RS485) protocol conversion 1 set of EtherCAT ports and 1 set of RS-485 ports The user manual and software for this gateway can be downloaded from the QR code sent with the product
		*Since there is only 1 set of RS-485 ports, multiple grippers cannot be controlled simultaneously. They can only be controlled individually.

# Electric Grippers Parallel Type

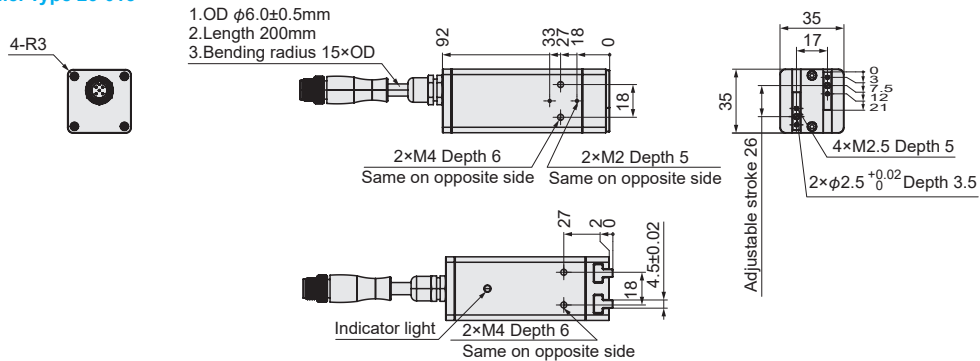
New Products



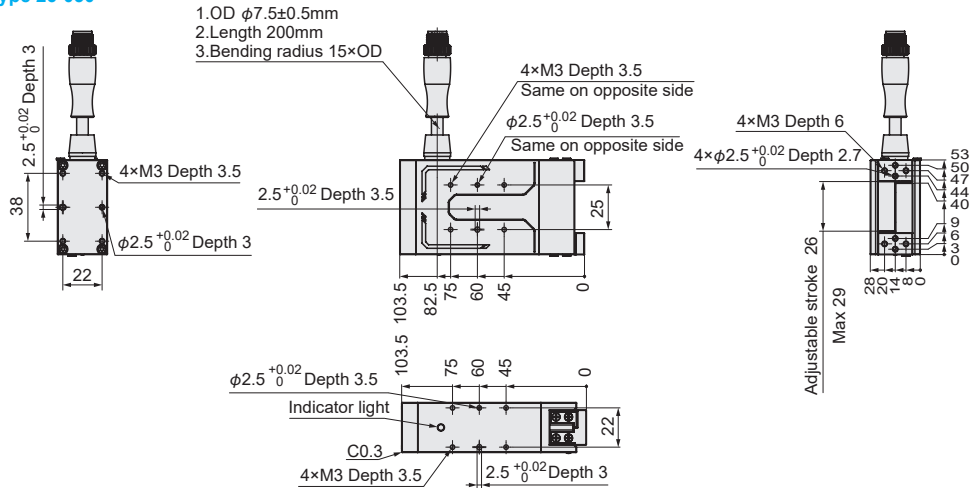
M Housing material	S Surface Treatment
Aluminum Alloy	Anodized

RoHS10

## Parallel Type 26-015



## Parallel Type 26-050



Type	Adjustable stroke (mm)	Clamping Force (N)	Communication Protocol	Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Open/Close Time (s)	Open/Close Speed (mm/s)	Positioning Repeatability (mm)	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
E-ELGPS (Connector Type)	26	015	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	35	35	92	0.25	0.3	43.3	$\pm 0.02$	IP40	Bottom Lead	DC24 $\pm 10\%$	0.85	0.4	9.6
		050		53	28	103.5	0.45	0.35	37.1	Side Lead			0.6		0.25	6	

\*1 The motor type is a servo motor with the built-in driver.  
\*2 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).  
\*3 The Electric Gripper does not include gripper fingers.  
\*4 The operating noise is less than 40dB.

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N-m)	Clamp Allowable Static Moment My (N-m)	Clamp Allowable Static Moment Mz (N-m)
E-ELGPS (Connector Type)	26	015	0.3	150	1.2	0.9	0.55
		050	1	200	3	2.5	3.5

# Electric Grippers Parallel Type

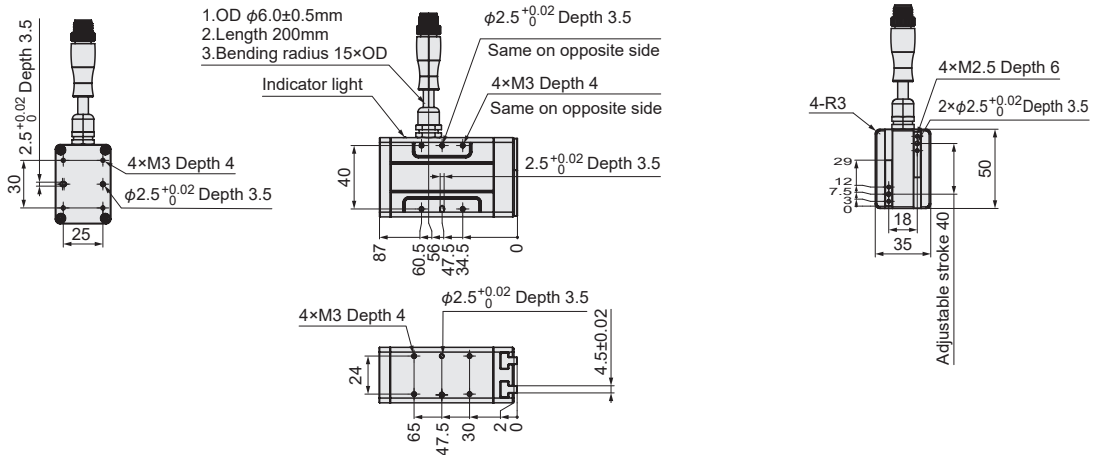
2

Electric Grippers

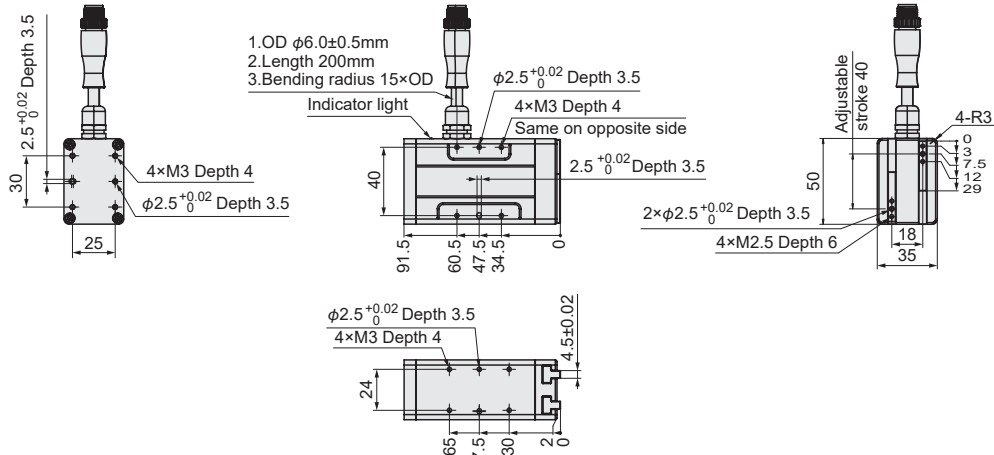
Electric Grippers

P.02-002

## Parallel Type 40-050



## Parallel Type 40-100



Type	Adjustable stroke (mm)	Clamping Force (N)	Communication Protocol	Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Open/Close Time (s)	Open/Close Speed (mm/s)	Positioning Repeatability (mm)	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
E-ELGPS (Connector Type)	40	050	T0: Modbus RTU (RS485)	L1 L3 L5 (Selectable Cable Length)	50	35	87	0.4	0.5	40	$\pm 0.02$	IP40	Side Lead	DC24 $\pm 10\%$	0.6	0.25	6
		100					91.5	0.44	0.9	22.2					0.85	0.4	9.6

\*1 The motor type is a servo motor with the built-in driver.  
 \*2 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).  
 \*3 The Electric Gripper does not include gripper fingers.  
 \*4 The operating noise is less than 40dB.

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N·m)	Clamp Allowable Static Moment My (N·m)	Clamp Allowable Static Moment Mz (N·m)
E-ELGPS (Connector Type)	40	050	0.8	200	2	1.5	2
		100	2				

How to search on website



1

By Type

Search on MISUMI official website

E-ELGPS

Search on MISUMI official website and get your product

2

By Keyword

Step 1 ▶

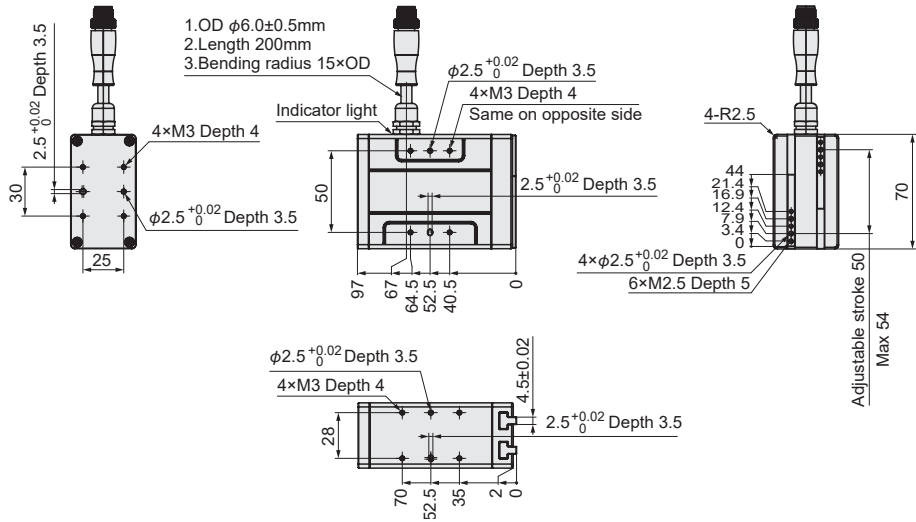
electric gripper

Step 2 \* Select Economy series

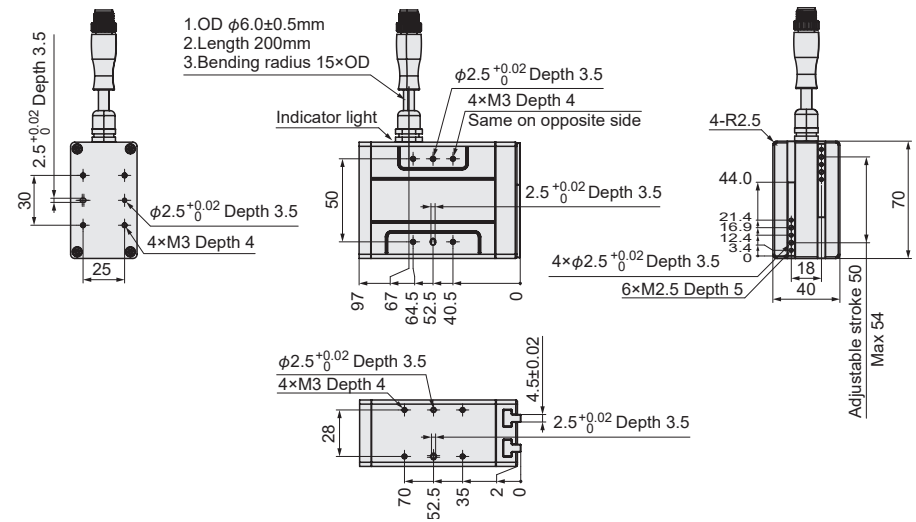
MISUMI

Only MISUMI Economy series

Parallel Type 50-060



Parallel Type 50-100



① Type	② Adjustable stroke (mm)	③ Clamping Force (N)	④ Communication Protocol	⑤ Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Open/Close Time (s)	Open/Close Speed (mm/s)	Positioning Repeatability (mm)	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
E-ELGPS (Connector Type)	50	060	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	70	40	97	0.8	0.6	41.6	±0.02	IP40	Side Lead	DC24 ±10%	0.85	0.4	9.6
		0.53						1.1	22.7	0.6					0.25	6	

\*1 The motor type is a servo motor with the built-in driver.  
 \*2 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).  
 \*3 The Electric Gripper does not include gripper fingers.  
 \*4 The operating noise is less than 40dB.

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N-m)	Clamp Allowable Static Moment My (N-m)	Clamp Allowable Static Moment Mz (N-m)
E-ELGPS (Connector Type)	50	060	1	200	2	1.5	2
		100	2		2.5	2	2.8

Ordering Example: ①Type · ②Adjustable stroke - ③Clamping Force - ④Communication Protocol - ⑤Cable Length  
 E-ELGPS40 - 050 - T0 - L5

# Electric Grippers Rotary Type

New Products



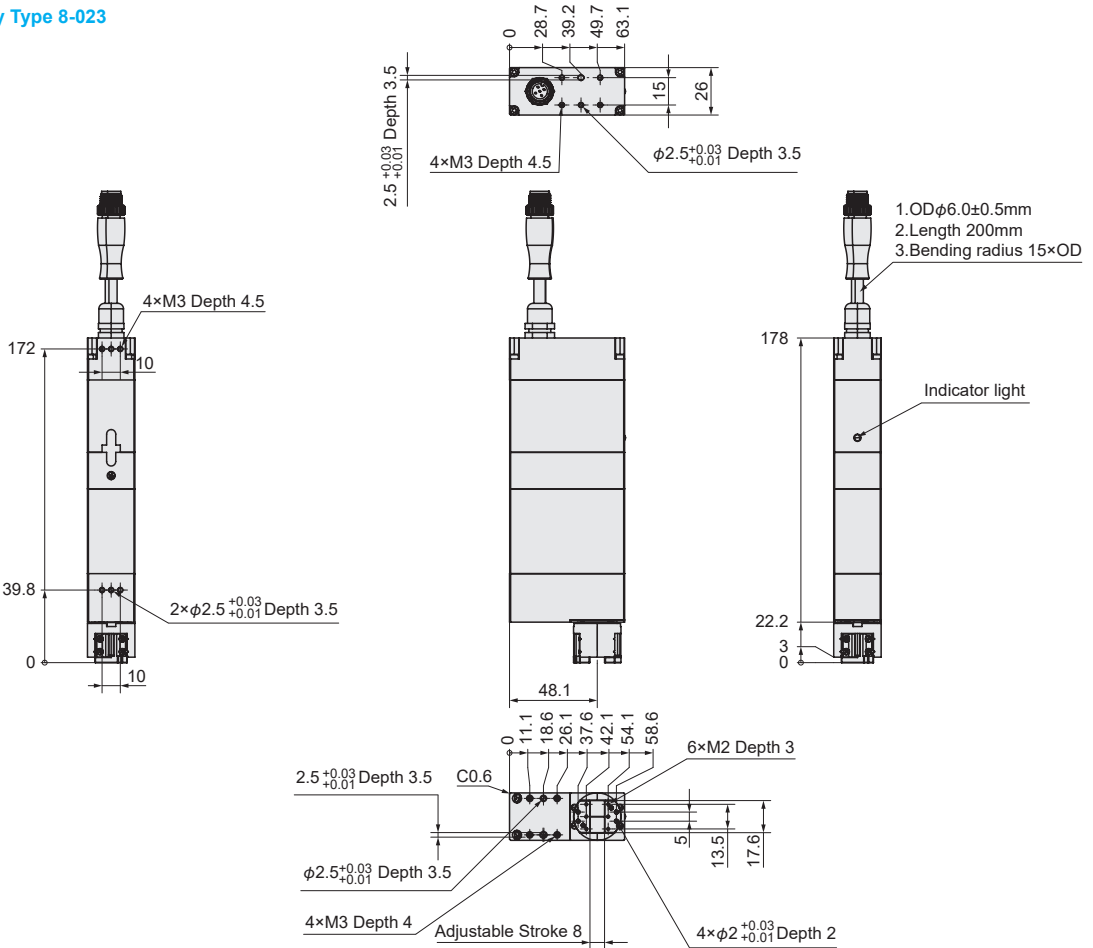
M Housing material	S Surface Treatment
Aluminum Alloy	Anodized

2

Electric Grippers

RoHS10

## Rotary Type 8-023

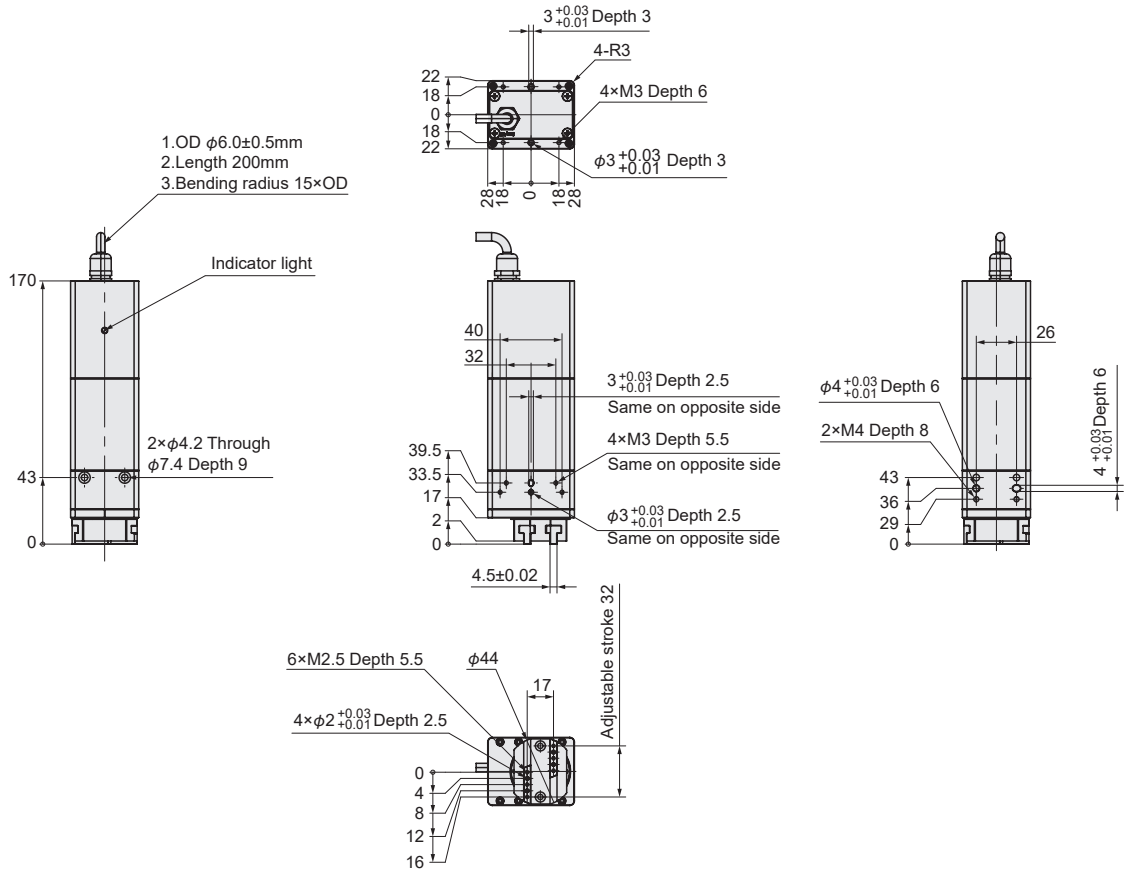


Type	Adjustable stroke (mm)	Clamping Force(N)	Communication Protocol	Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Rated Torque (N·m)	Peak Torque (N·m)	Open/Close Time (s)	Open/Close Speed (mm/s)	Rotary Speed (°/s)	Positioning Repeatability (mm)	Rotational Repeatability	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
E-ELGPRS (Connector Type)	8	023	T0: Modbus RTU (RS485)	L1 L3 L5 (Selectable Cable Length)	63.1	26	178	0.6	0.12	0.3	0.15	26.6	1500	±0.02	±0.5°	IP40	Bottom Lead	DC24 ±10%	2	0.4	9.6

- \*1 Rotary Gripper can rotate infinitely in one direction, supports both clockwise and counterclockwise rotation.
- \*2 The motor type is a servo motor with the built-in driver.
- \*3 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).
- \*4 The Electric Gripper does not include gripper fingers.
- \*5 The operating noise is less than 70dB.

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N·m)	Clamp Allowable Static Moment My (N·m)	Clamp Allowable Static Moment Mz (N·m)
E-ELGPRS (Connector Type)	8	023	0.3	100	1.5	1.5	1.5

Rotary Type 32-100



Type	Adjustable stroke (mm)	Clamping Force(N)	Communication Protocol	Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Rated Torque (N·m)	Peak Torque (N·m)	Open/Close Time (s)	Open/Close Speed (mm/s)	Rotary Speed (°/s)	Positioning Repeatability (mm)	Rotational Repeatability	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
<b>E-ELGPRS</b> (Connector Type)	32	100	T0: Modbus RTU (RS485)	L1 L3 L5 (Selectable Cable Length)	56	44	170	0.7	0.3	1.5	0.5	32	1000	±0.02	±0.5°	IP40	Bottom Lead	DC24 ±10%	4	0.6	14.4

\*1 Rotary Gripper can rotate infinitely in one direction, supports both clockwise and counterclockwise rotation.  
 \*2 The motor type is a servo motor with the built-in driver.  
 \*3 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).  
 \*4 The Electric Gripper does not include gripper fingers.  
 \*5 The operating noise is less than 70dB.

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N·m)	Clamp Allowable Static Moment My (N·m)	Clamp Allowable Static Moment Mz (N·m)
<b>E-ELGPRS</b> (Connector Type)	32	100	1.5	200	2	2	2

**Ordering Example** ①Type · ②Adjustable stroke - ③Clamping Force - ④Communication Protocol - ⑥Cable Length  
**E-ELGPRS32 - 100 - T0 - L5**

How to search on website

**1 By Type:** Search on MISUMI official website and get your product  
 Search on MISUMI official website:

**2 By Keyword:** Step 1 >   
 Step 2 > Select Economy series  
 MISUMI  
 Only MISUMI Economy series

# Electric Grippers Vacuum Suction Type

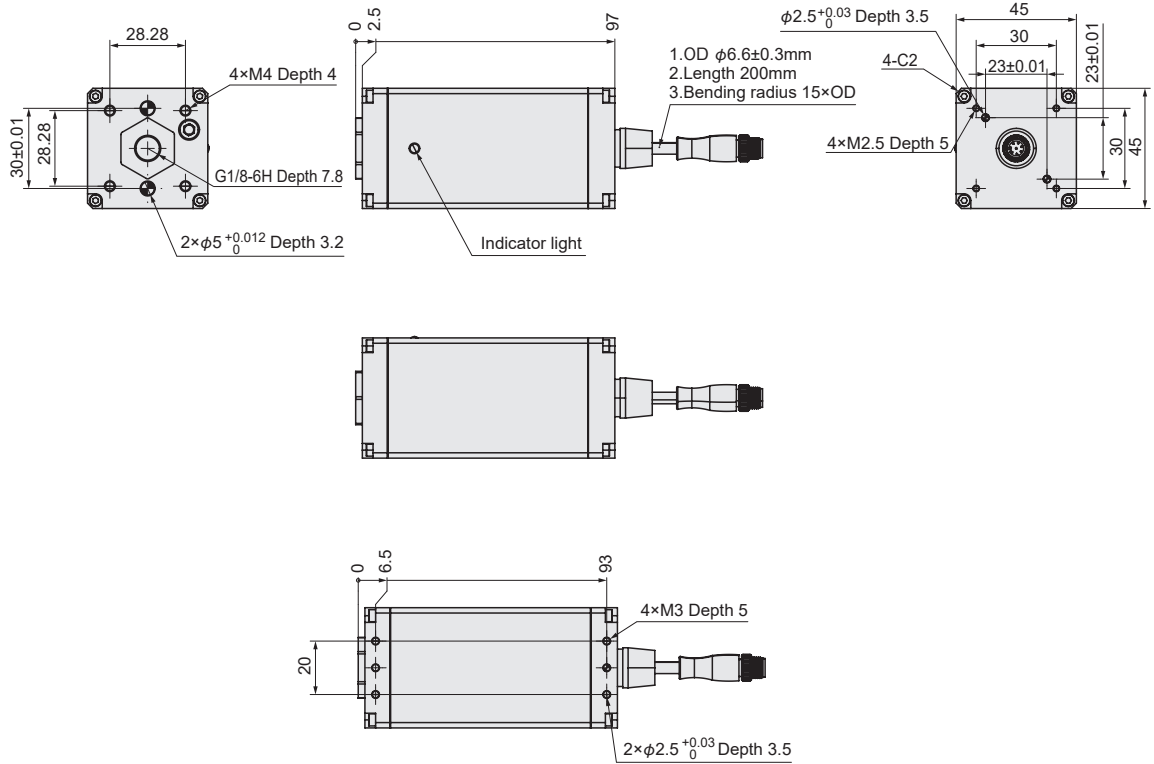
New Products

M Housing material	S Surface Treatment
Aluminum Alloy	Anodized



RoHS10

## Suction Type 01



Type	Maximum Allowable Load (kg)	Communication Protocol	Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Protection Level	Vacuum Pressure (kPa)	Maximum Flow L/min	Fastest Suction/Release Time(s)	Rated Voltage (V)	Rated Current (A)	Peak Current (A)	Rated Power (W)
E-ELGVS (Connector Type)	01	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	45	45	97	0.3	IP40	-10 to -60	2.5	0.1/0.1	DC24 ±10%	0.13	0.3	3.5

\*1 Real-time vacuum compensation for suction stability.

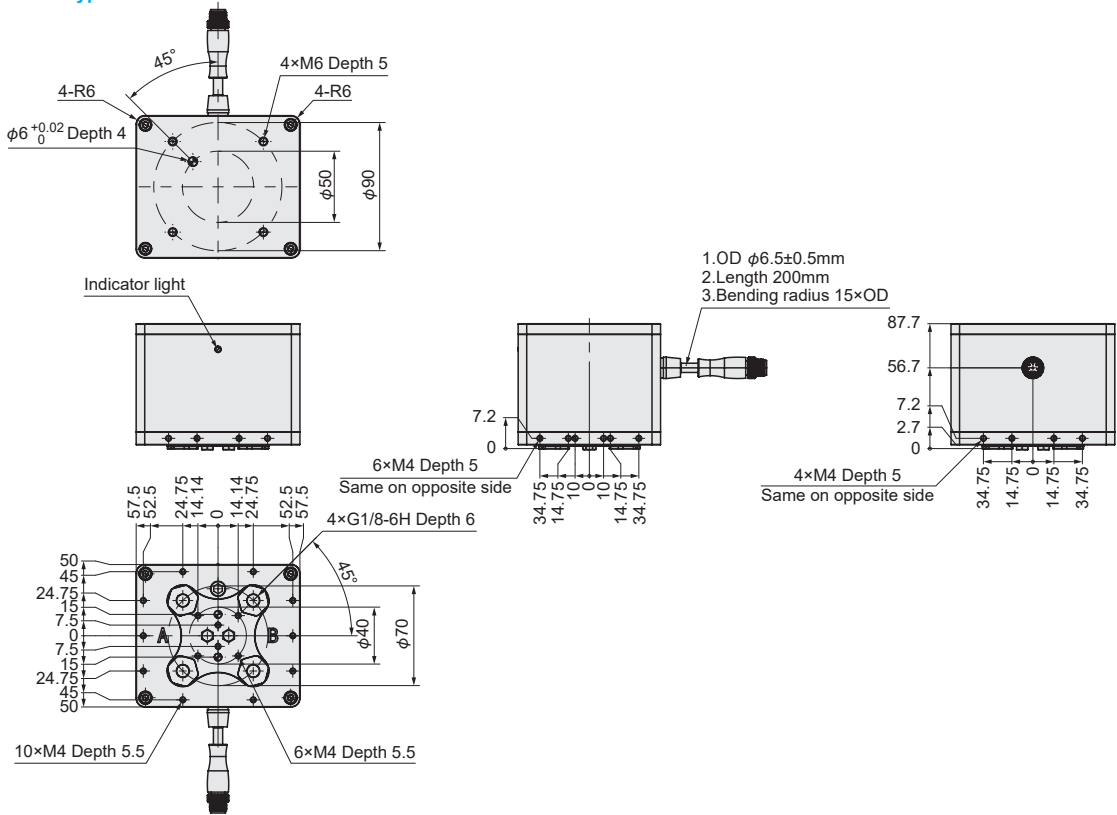
\*2 The Vacuum Gripper has built-in vacuum pump.

\*3 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).

\*4 The Vacuum Gripper does not include suction cups.

\*5 The operating noise is less than 70dB.

Suction Type 08



E-ELGVS08 has two built-in independent chambers A/B, which can be independently controlled to achieve 2 open and 2 closed.

① Type	② Maximum Allowable Load (kg)	③ Communication Protocol	④ Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Protection Level	Vacuum Pressure (kPa)	Maximum Flow L/Min	Fastest Suction/Release Time(s)	Rated Voltage (V)	Rated Current (A)	Peak Current (A)	Rated Power (W)
E-ELGVS (Connector Type)	08	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	115	100	87.7	1.4	IP56	-10 to -70	10	0.4/0.2	DC24 ±10%	0.5	3.8	12

- \*1 Real-time vacuum compensation for suction stability.
- \*2 The Vacuum Gripper has built-in vacuum pump.
- \*3 The recommend operating environment is 5~40°C, with humidity below 85% RH (no condensation).
- \*4 The Vacuum Gripper does not include suction cups.
- \*5 The operating noise is less than 70dB.

Ordering Example

① Type · ② Maximum Allowable Load - ③ Communication Protocol - ④ Cable Length  
**E-ELGVS01 - T1 - L5**

How to search on website

**1 By Type**

Search on MISUMI official website

**E-ELGVS**

Search on MISUMI official website and get your product

**2 By Keyword**

Step 1 ▶

**electric gripper**

Step 2 ▶ Select Economy series

MISUMI

Only MISUMI Economy series

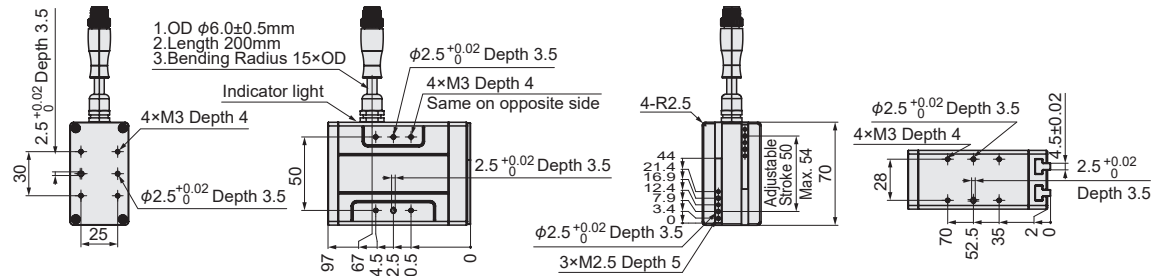


1 Type	2 Adjustable Stroke (mm)	3 Clamping Force (N)	4 Communication Protocol	5 Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Open / Close Time (s)	Open / Close Speed (mm/s)	Positioning Repeatability (mm)	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
E-ELGPPHS (Connector Type)	40	050	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	50	35	110	0.4	0.56	35.7	±0.02	IP40	Side Lead	DC24 ±10%	0.6	0.25	6
		0.44						1	20	0.85					0.4	9.6	

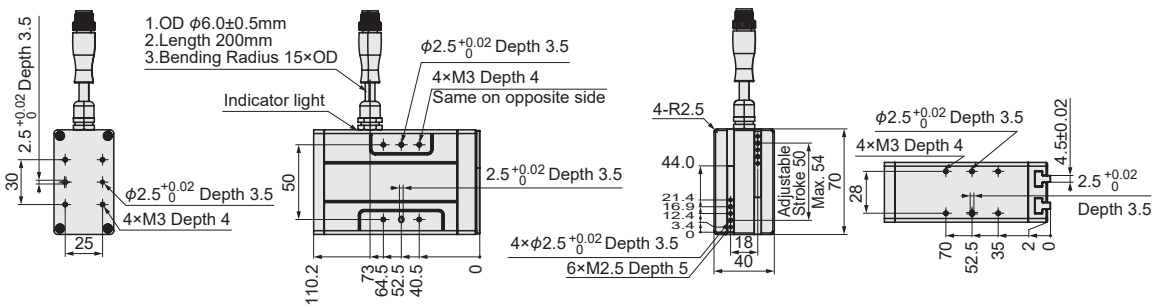
- \*1 The motor type is a servo motor with a built-in driver
- \*2 The operating environment is 5~40°C, 85%RH or less (no condensation)
- \*3 The shipped product does not contain the gripper finger.
- \*4 Operating noise < 40dB
- \*5 The height is 18.5mm / 23mm higher than the standard electric gripper.

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N-m)	Clamp Allowable Static Moment My (N-m)	Clamp Allowable Static Moment Mz (N-m)
E-ELGPPHS (Connector Type)	40	050	0.8	200	2	1.5	2
		100	2				

Parallel Type with Brake 50-060



Parallel Type with Brake 50-100



1 Type	2 Adjustable Stroke (mm)	3 Clamping Force (N)	4 Communication Protocol	5 Cable Length (m)	Length (mm)	Width (mm)	Height (mm)	Weight (kg)	Open / Close Time (s)	Open / Close Speed (mm/s)	Positioning Repeatability (mm)	Protection Level	Lead Wire Position	Rated Voltage (V)	Peak Current (A)	Rated Current (A)	Rated Power (W)
E-ELGPPHS (Connector Type)	50	060	T1: Modbus RTU(RS485)+I/O	L1 L3 L5 (Selectable Cable Length)	70	40	97	0.8	0.6	41.6	±0.02	IP40	Side Lead	DC24 ±10%	0.85	0.4	9.6
		110.2					0.63	1.1	22.7	0.6					0.25	6	

- \*1 The motor type is a servo motor with a built-in driver
- \*2 The operating environment is 5~40°C, 85%RH or less (no condensation)
- \*3 The shipped product does not contain the gripper finger.
- \*4 Operating noise < 40dB
- \*5 E-ELGPPHS50-060 is the same product as the standard type E-ELGPPS50-060
- \*6 The height of E-ELGPPHS50-100 is 13.2mm higher than the standard type E-ELGPPS50-100. Please refer to the specification table or product drawing for details

Type	Adjustable stroke (mm)	Clamping Force (N)	Max Load (kg)	Vertical Allowable Static Load Fz (N)	Clamp Allowable Static Moment Mx (N-m)	Clamp Allowable Static Moment My (N-m)	Clamp Allowable Static Moment Mz (N-m)
E-ELGPPHS (Connector Type)	50	060	0.8	200	2	1.5	2
		100	2				

Ordering Example: 1 Type · 2 Adjustable Stroke - 3 Clamping Force - 4 Communication Protocol - 5 Cable Length  
E-ELGPPHS50 - 060 - T1 - L5